

ROBOTICS IN STEM





FUN, ENGAGING & SKILLING



ENABLES LIFE - SKILLS LIKE COMMUNICATION, TEAMWORK



CONNECTS TECHNOLOGY TO SCIENCE



TABLE OF CONTENTS

1.	Robotics in STEM: Summary of Bill of Material	5
2.	Scope Of MTC Services	8
	2.1. Train The Trainer	8
	2.2. Mentoring The Trainers	8
	2.3. Workshops And Competition	8
3.	Scope Of The Customer	9
	3.1. Technical Scope	9
	3.2. Administrative Scope	9
4.	Bill of Material: Minirobot	11
	4.1. Robot	11
	ROBOT SPECIFICATION	12
	4.2. Controller	12
	4.3. Control Software	13
	4.4. User Manual	13
	4.5. General Manual	13
5.	Bill of Material: Minirobot (Project)	13
	5.1. Robot	13
	ROBOT SPECIFICATION	14
	5.2. Controller	14
	5.3. Control Software	14
	5.4. User Manual	14
	5.5. General Manual	14
	5.6. Assembly Manual	14



6.	Bill o	f Material: M-Robot15
	Intro	duction15
	Obje	ctives15
	Softv	vare Features15
	Man	ual15
	Train	ing Skills15
7.	Bill o	f Material: AristoSIM17
	Intro	duction17
	Obje	ctives
	Softv	vare Features17
	Man	ual18
	Train	ing Skills
	In-bu	ilt Applications:18
8.	Bill o	f Material: Robot Application Kit for Technology19
9.	Bill o	f Material: Robot Application Kit for Engineering19
10.	Bill	of Material: Robot Application Kit for Science & Maths20
11.	Uti	lities Required At Site20
1	1.1.	Utilities for Mini Robot20
1	1.2.	Utilities for M-Robot & AristoSim20
12.	Bill	of Material: STEM Courseware21
1	2.1.	Robotics in STEM Courseware21
1	2.2.	Robotics in STEM Courseware for Class 822
1	2.3.	Robotics in STEM Courseware for Class 9



12.4.	Robotics in STEM Courseware for Class 10	26
12.5.	Robotics in STEM Courseware for Class 11	29
12.6.	Robotics in STEM Courseware for Class 12	32
13. De	livery Schedule	35
13.1.	Delivery Schedule	35
13.2.	Commissioning and Demonstration	36
13.3.	Warranty	36
13.4.	Site Clearance by MTC:	36
14. Su	mmary Of Commercial Offer	37
Contact	Details	



Category	Туре	Scope of Supply & Services	ltem
Supply	ly Hardware Robotics in STEM Kit: Mini Robot Mini Robot (Project		Mini Robot
			Mini Robot (Project)
			Robot Application Kit for
			Technology
			Robot Application Kit for
			Engineering
			Robot Application Kit for Science &
			Maths
Supply	Software	Robotics in STEM Software	M-Robot
			AristoSIM
Supply	Courseware	Courseware: Interactive eLearning licenses	STEM Courseware
Supply	Courseware	Courseware: PDF Books	STEM Courseware
Services	Services	Commissioning & Demonstration	
Services	Services	Warranty	
Services	Services	Mentoring & Monitoring	
Services	Training	Train the Teachers	
Services	Services	Workshop and Competitions	

1. ROBOTICS IN STEM: SUMMARY OF BILL OF MATERIAL

	Robotics in STEM							
Sno	Item Sub Item Description			Qty	UoM			
		Robot	5 axes miniature industrial robot in a fully assembled condition	1	No			
		Controller	Robot controller	1	No			
1	Mini Robot	Control Software	Robot programming and control software. PC is not included for this	1	License			
		User Manual	User manual will be supplied on how to program and use the robot	1	PDF Doc			
			General operating manual along with details of the product and essential					
		General Manual	drawings	1	PDF Doc			
		Robot Mechanical Sub Assembly	The 5 links of the robot will be supplied in different stages of sub- assembly	1	Set			
		Robot Electrical Parts	Electrical parts such as motors and gripper for the assembly	1	Set			
2	Mini Robot	Robot Connectors	Electrical connectors and insulation required for assembly of robot	1	No			
	(Project)	Controller	Robot controller	1	No			
		Control Software	Robot programming and control software. PC is not included for this	1	License			
		User Manual	User manual will be supplied on how to program and use the robot	1	PDF Doc			



		General Manual	General operating manual along with details of the product and essential drawings	1	PDF Doc
Assembly Manual		Assembly Manual	This will be supplied as part of the application projects under STEM	1	PDF Doc
3	M-Robot	Software	Robot Programming Software	10	License
4	AristoSIM	Software	Robot application software	10	License
5	Robot Application Kit for Technology	Base Plate Pick & Place Palletizing Drawing Writing Writing Mobile Robot Motors & Operation Line Tracer Circuit Design - PCB Circuit Design - Broad Baard		1	Cat
		Bread Board	In an assembled & ready to use condition	1	Set

	Robotics in STEM								
Sno	Item	Sub Item	Description	Qty	UoM				
		Base Plate	To be assembled						
		Pick & Place	To be assembled						
		Palletizing	To be assembled						
	Dahat	Drawing	To be assembled						
6	Robot Application Kit	Writing	To be assembled						
0	for Engineering	Mobile Robot	To be assembled						
		Motors & Operation	To be assembled						
		Line Tracer	To be assembled						
		Circuit Design - PCB	To be assembled						
		Circuit Design - Bread Board	To be assembled	1	Set				
	Robot	Maths Concepts	As relevant for Class 8-12						
7	Application Kit								
	Maths	Physics concepts	As relevant for Class 8-12	1	Set				
		Science for Class 8		10	License				
		Technology for Class 8		10	License				
		Mathematics for Class 8	ELearning / PDF Book	10	License				
Q	STEM	Science for Class 9	(Perpetual licenses) will	10	License				
0	Courseware	Technology for Class 9	be delivered with the	10	License				
		Engineering for Class 9	delivery of the product.	10	License				
		Mathematics for Class 9		10	License				
		Science for Class 10		10	License				



Technology for Class 10	10	License
Engineering for Class 10	10	License
Mathematics for Class 10	10	License
Science for Class 11	10	License
Technology for Class 11	10	License
Engineering for Class 11	10	License
Mathematics for Class 11	10	License
Science for Class 12	10	License
Technology for Class 12	10	License
Engineering for Class 12	10	License
Mathematics for Class 12	10	License



2. SCOPE OF MTC SERVICES

MTC shall provide the following services along with the STEM labs proposed in this document in order to enhance the student engagement with the program and the delivery of skills by faculty to the students. The services are defined in this section.

2.1. TRAIN THE TRAINER

The teachers will be trained on the STEM labs. The training will cover the STEM curriculum offered by MTC and training on the usage of the kits. Each training will be for duration of 5 days at a centralized location. The number of teachers from each school is limited to: 2 teachers from Science, 2 from Mathematics and 1 from Computer Science.

2.2. MENTORING THE TRAINERS

For every 10 schools, one mentor will be provided (to be firmed up based on mutual discussion, considering factors like distance, transportation etc.,) for continuous support to the teaching faculty at the schools. The mentor will spend maximum of 2 working days (in a month) at each school throughout the warranty period. The role of the mentor is to act as a facilitator and guide for the teachers to implement the STEM curriculum.

2.3. WORKSHOPS AND COMPETITION

MTC shall assist in conducting workshops and competitions via the mentors. This segment covers details about how these events should be planned and scheduled. One customer event coordinator must be assigned for each workshop. One workshop and competition will be conducted for every 15 schools (need to be discussed and firmed up). MTC Scope of work is limited to the following:

- □ The maximum Number of student participation in each project is limited to five.
- □ There are two levels of participation: Level1 (Class 8,9,10) & Level2 (Class 11 & 12)
- □ Marketing Material: Art work for posters and banner will be given by MTC.
- □ The layout of the workshop will be given by MTC along with the program schedule. The customer has to coordinate with the workshop school for arranging the same.
- Location and Layout
- □ Local arrangement must be taken care by the school management (recurring expense)
- □ MTC will capture the event (as photographs) and will offer you the digital USB after the date of the event along with a report.
- □ Prize Category: Each level of project will be awarded as Winner and Runner up prize. Along with the prize certificates for each winning student will be given.
- □ Certificates to all the participating schools will be given.
- □ Security to the event: Safety aspects must be taking care by the customer.
- \Box No. of Participants: 75 100
- □ No. of Visitor Approximately 1000 nos. Customer should arrange for the facilities to manage the visitors.

Selection and Evaluation of Projects displayed at the event: A PowerPoint presentation and a write up of the project (limited up to 250 words) must be submitted by the participating school. The selection process of the winner is done by MTC. The submission date will be given in the Artwork.

Selection criteria:

- □ Innovative and creative thinking
- Team work
- □ Application of technology/ concept relevance to the real world



3. SCOPE OF THE CUSTOMER

3.1. TECHNICAL SCOPE

- □ The equipment shall be kept in the Computer Science lab
- □ Power supply with proper earthing
- Personal Computer (10 no's with LAN internet connection) with technical specifications as per Bill of Materials. The same is also listed below.
- □ Teacher's computer should have internet connection
- □ Table for keeping the robot (2 no's)
- □ Projector for presentation
- □ License key (dongle) for accessing the software
- □ Internet connection is allowed only for teachers

Desktop computer on network as per the below specifications:

- Operating System : Windows 7 Professional or higher, Two free USB ports
- Processor: Intel 2,8 GHz or higher, RAM : at least 4 GB, 1 DVD Drive for software installation
- Graphic Card : NVIDIA GeForce at least 1 GB or equivalent, Recommended: 19" TFT Mon

Power Supply: Stable power supply is required as mentioned in the robot specifications.

3.2. Administrative Scope

- □ List of schools to be given along with the Purchase Order as per Annexure 1
 - The school should be selected that the requirement of the technical scope is met by the school
- Sensitization and information to the selected schools to be done within 2 weeks of Purchase Order release
- During Train the Teachers Program:
 - The customer has to submit the details of the teachers who have to be trained as per the format given in **Annexure 2.**
 - \circ $\;$ The customer has to organise for the teachers to come to the centralised training location (host School).
 - Any and all expense that will be incurred by the teachers or the host schools for the training has to be borne by the customer.
 - \circ Refreshment to be provided during the training. (Two tea breaks and one lunch)
 - Training Timing: 9AM till 4 PM
 - \circ $\;$ The host school should be equipped with the following training facilities :
 - Projector
 - White Board with ink pens
 - Computer lab with 15 -20 computers
 - Stable power supply and earthing should be available during training
- Workshop and Competition: MTC will give the number of workshops and competitions it will conduct during the period of 1 year. Example : For 150 schools MTC will conduct 10 workshops and competitions. In order to facilitate this event, the customer should
 - Select the Venue and give it along with the purchase order. Refer Annexure 3 for format. The venue has to be from one of the schools where the supply will be made. Two schools from the district cannot be selected. The school selected to host the



competition is known as the "Workshop School." The Workshop School should have the infrastructure of a large assembly hall which can accommodate a display of total 30 projects. One school from a group of five adjacent districts must be selected.

- Invitation of the Chief Guest should be done by the Workshop School. Mementos for the visiting dignitaries should be arranged.
- 15 Schools will participate in the event including the Workshop School. Maximum of 2 project per school will be allowed for display. For each participating school, One teacher along with two student per project will be allowed for the competition.
- Participating Schools will select the two project and the teams that they wish to display at the event.
- \circ The workshop is a day event : From 11 AM till 3 PM (we can work on mutual time)
- Any and all expense that will be incurred by the teachers, students & the Workshop schools for the event has to be borne by the customer.
- Refreshments to be provided (for the dignitaries, participants and support personnel involved in the workshop) during the Event and the same will be in the scope of the Workshop School. (Two tea breaks and one lunch)
- Workshop School should take care of facilities such as lighting requirements, fans, installation of speakers, PA system, number of mike etc.,
- Artwork given by MTC should be printed and displayed in the event and distributed across the region and schools by the customer. Artwork will be given for posters and banners.
- The customer should market the event to all the schools under school education coming under their district. Advertisement of the event has to done by the customer.
- Promotion of the event, Media coverage, Photography and video to be taken care by the Customer.
- Any and all Statutory permission required for conducting this event is to be obtained by the customer
- \circ Safety norms should be followed and ensured as per the Government regulation.



4. BILL OF MATERIAL: MINIROBOT

4.1. Ковот

Minirobot is a miniature scale down model of a 5 axes industrial robot. This modular table-top 5 axis articulated robot consists of light-medium duty stepper motors for all joint actuation as a special feature the gripper is driven by a RC servo motor. The controller consists of easy pluggable type cable for swift interfacing and online programming thru' dedicated application for various applications control.



Training and control of an articulated robot for broad rationale applications or special purpose application thru Jog (Teach method) as well as Auto mode control for Fatigue tasks.

This robot is offered with a series of application kits and courseware that is meant for delivering skills related to STEM Labs. In the following pages, the different aspects of the Robotics in STEM Lab solution will be detailed out.



ROBOT SPECIFICATION

4.2. CONTROLLER

The robot controller offered is a compact and mobile controller that is east to install and connect. The controller has been built on international safety standards and each component used has been selected to meet these standards.

		Metric Units		SAE Units
Controller		PC based Stepper Control algorithm		PC based Stepper Control algorithm
Control Software		Specially developed Robot Programming Language.		Specially developed Robot Programming Language
Path Type		Point-to-Point		Point-to-Point
Communication		PC USB Port		PC USB Port
Accessories & Input/output		8 digital Inputs/Outputs		8 digital Inputs/Outputs
Power supply		110V/ 230V AC, 50/60 Hz, 5A		110V/ 230V AC, 50/60 Hz, 5A
Repeatability	mm	1	in	0.04
Resolution	mm	1	in	0.04
Weight of Robot Controller	kg	4 without control box	lbs	8.8



4.3. CONTROL SOFTWARE

The control software is M-Robot. M-Robot is user-friendly 3D software for robot programming. This software gives the flexibility to design your applications and import them into the 3D software for simulation. Ready-made applications are available to train the user in the operations of the robot such as movement, programming and code generation. M-Robot has graphics which enable you to visualize the robot from various angles as the robot moves in the simulated application. It allows you to watch your code at work. Thus, finalizing your program for operation and protecting the robot from accidents. Once your programs are ready and verified in an offline and online Software, the students can use it in the online mode to work the robot.

4.4. USER MANUAL

User manual is given in the PDF format. The user manual comprises of how to use the robot, programming of the robot.

4.5. GENERAL MANUAL

General manual is given in the PDF format. The manual comprises of general Dos and Don'ts of the product along with generic information about the product.

5. BILL OF MATERIAL: MINIROBOT (PROJECT)

5.1. Ковот

Minirobot is a miniature scale down model of a 5 axes industrial robot. This modular table-top 5 axis articulated robot consists of light-medium duty stepper motors for all joint actuation as a special feature the gripper is driven by a RC servo motor. The controller consists of easy pluggable type cable for swift interfacing and online programming thru' dedicated application for various applications control.

The robot is supplied in a dis-assembled condition as separate joints. The primary purpose of this is to learn skills on assembly, electronics and programming.



Training and control of an articulated robot for broad rationale applications or special purpose application thru Jog (Teach method) as well as Auto mode control for Fatigue tasks.

This robot is offered with a series of application kits and courseware that is meant for delivering skills related to STEM Labs. In the following pages, the different aspects of the Robotics in STEM Lab solution will be detailed out.



ROBOT SPECIFICATION

5.2. CONTROLLER

The robot controller offered is a compact and mobile controller that is east to install and connect. The controller has been built on international safety standards and each component used has been selected to meet these standards. Here again the controller is supplied in a dis-assembled condition. Connectors, motors etc. are supplied and the exercises are focussed around building, assembling the robot controller

		Metric Units		SAE Units
Controller		PC based Stepper Control algorithm		PC based Stepper Control algorithm
Control Software		Specially developed Robot Programming Language.		Specially developed Robot Programming Language
Path Type		Point-to-Point		Point-to-Point
Communication		PC USB Port		PC USB Port
Accessories & Input/output		8 digital Inputs/Outputs		8 digital Inputs/Outputs
Power supply		110V/ 230V AC, 50/60 Hz, 5A		110V/ 230V AC, 50/60 Hz, 5A
Repeatability	mm	1	in	0.04
Resolution	mm	1	in	0.04
Weight of Robot Controller	kg	4 without control box	lbs	8.8

5.3. CONTROL SOFTWARE

The control software is M-Robot. M-Robot is user-friendly 3D software for robot programming. This software gives the flexibility to design your applications and import them into the 3D software for simulation. Ready-made applications are available to train the user in the operations of the robot such as movement, programming and code generation. M-Robot has graphics which enable you to visualize the robot from various angles as the robot moves in the simulated application. It allows you to watch your code at work. Thus, finalizing your program for operation and protecting the robot from accidents. Once your programs are ready and verified in an offline and online Software, the students can use it in the online mode to work the robot.

5.4. USER MANUAL

User manual is given in the PDF format. The user manual comprises of how to use the robot, programming of the robot.

5.5. GENERAL MANUAL

General manual is given in the PDF format. The manual comprises of general Dos and Don'ts of the product along with generic information about the product.

5.6. ASSEMBLY MANUAL

The assembly manual is supplied with details on how to assemble the different parts of the robot and the required connectivity details etc. This is to be used as a reference for the teacher. The exercises to build the robot and the different projects focused around the robot construction are detailed in the courseware.



6. BILL OF MATERIAL: M-ROBOT

INTRODUCTION

M-Robot is user-friendly 3D software for robot programming. This software gives the flexibility to design your applications and import them into the 3D software for simulation. Ready-made applications are available to train the user in the operations of the robot such as movement, programming and code generation. M-Robot has graphics which enable you to visualize the robot from various angles as the robot moves in the simulated application. It allows you to watch your code at work. Thus, finalizing your program for operation and protecting the robot from accidents.

OBJECTIVES

Learn and Control an articulated robot for broad applications or special purpose application through robot control functions, and through online and offline programming.

Once your programs are ready and verified in an offline and online Software, the students can use it in the online mode to work the robot.

M-Robot is 3D Software. This 3D Software can support three Models of Robot simulation:

- □ Aristo Robot 6 Axes
- Mini Robot 5 Axes
- SCARA Robot 4 Axes

SOFTWARE FEATURES

- □ Offline simulation software
- □ Easy to use & simulate user friendly design
- □ Readymade applications in 3D environment 3D environment for robot and world objects
- □ User friendly Teach pendant to program
- Robot Commands include Import/Export robot programs, Axial & Cartesian movement of robot, Robot program flow control, Commands such as Point to point (Cartesian / Axial), Path (Line / Spline / Circle)
- Design of applications through CAD Explorer which includes Create/Import models, Insert standard robot pedestal & table, Extensive library of Tools, Tool Library (inbuilt / custom), Grasping CAD objects, Machine status display, Tool path tracer (Tool ON / OFF)
- □ Applications package is readily available. Applications can also be designed as per user requirements.

MANUAL

Software Manual for programming is built and offered with the software as a PDF file.

TRAINING SKILLS

The following training skills are delivered using this product:

- □ Introduction to Robot programming
- □ Interpret of robot inter-joints, kinematics
- □ Learn about Off-line programming techniques
- □ Robot movement, Individual axis movement, Cartesian movement
- □ Jogging speed, Simulation speed
- □ Robot Programming techniques Programming using Joint control or Cartesian control.
- Easy Teach through approach using diverse commands



- □ Programming using Lead through & Teach method.
- □ Merits & demerits of each programming type based on application.
- □ Ability to Trace Robot path movement
- Programming perspective based on the application being designed
- □ Learn about the Possibility of Faulty programming and corrective methods.
- □ Learn about the risk of flawed/ unsafe programming
- □ Understand correct programming methods by simulating virtually all programming methods.



7. BILL OF MATERIAL: ARISTOSIM

INTRODUCTION

This ARISTO SIM is designed to control a 6-Axis articulated robot in a virtual environment once the simulated program is satisfactory and meets the required process the program can be loaded to the real-time robot (ARISTO) to carry out these experiments. Thus ARISTO SIM can work as a standalone system and can also be combined with Real-time Robot (ARISTO) for Training of Engineering students and Industry Professionals.

The industrial robot arm functions like linear, circular, spline path generation, joint & Cartesian movement of robot can be simulated. ARISTO SIM also includes features like Import/Export of CAD files in STEP format, selection of various types of End-effectors from the Tools library, creation of rectangular box, cylinder are also possible for work cell development and it also includes many practice programs for engineering students to learn about the use of Robots and its applications.



OBJECTIVES

Programming and virtual simulation of 6-axis articulated robot for broad rationale applications or (inbuilt) special purpose application through Jog (Teach method) or Auto mode with feasibility to import/export components and grippers according to the type of application to be handled. Discern & understand types of gripper's & effective robot programming methodology.

SOFTWARE FEATURES

- Offline simulation software
- □ Easy to use & simulate user friendly design
- □ Readymade applications in 3D environment 3D environment for robot and world objects
- □ User friendly Teach pendant to program



- Robot Commands include Import/Export robot programs, Axial & Cartesian movement of robot, Robot program flow control, Commands such as Point to point (Cartesian / Axial), Path (Line / Spline / Circle)
- Design of applications through CAD Explorer which includes Create/Import models, Insert standard robot pedestal & table, Extensive library of Tools, Tool Library (inbuilt / custom), Grasping CAD objects, Machine status display, Tool path tracer (Tool ON / OFF)
- □ Applications package is readily available. Applications can also be designed as per user requirements.

MANUAL

Software Manual for programming is built and offered with the software as a PDF file.

TRAINING SKILLS

The following training skills are delivered using this product:

- □ Introduction to Robot programming
- □ Interpret of robot inter-joints, kinematics
- □ Learn about Off-line programming techniques
- □ Robot movement, Individual axis movement, Cartesian movement
- □ Jogging speed, Simulation speed
- □ Robot Programming techniques Programming using Joint control or Cartesian control.
- □ Easy Teach through approach using diverse commands.
- □ Programming using Lead through & Teach method.
- □ Merits & demerits of each programming type based on application.
- □ Ability to Trace Robot path movement
- □ Programming perspective based on the application being designed
- □ Learn about the Possibility of Faulty programming and corrective methods.
- □ Learn about the risk of flawed/ unsafe programming
- □ Understand correct programming methods by simulating virtually all programming methods.

IN-BUILT APPLICATIONS:

The following applications are built in the software and ready to use for the trainees. This is to make the understanding easier and better and thus encourage the trainee to build more applications – both fun and relevant to today's generic usage of robots

- MACHING & FABRICATION USING ROBOTS: Arc Welding, Laser cutting, Grinding, Deburring and Polishing
- MATERIAL HANDLING & ASSEMBLY USING ROBOTS: Machine tending, Loading / Unloading, Assembly, Pick and Place
- □ ARTIFICAL INTELLIGENCE USING ROBOT: Inspection and detection, Actions based on recognition, Actions that require cognition and decision making
- □ FUN WITH ROBOTS: Different applications such as painting, Colouring an object, Assembling a Toy, Dancing to music etc.



8. BILL OF MATERIAL: ROBOT APPLICATION KIT FOR TECHNOLOGY

The following application kit is offered as Robot Application Kit. This is offered as a fully assembled kit for the Trainees to program the application. The STEM Courseware related to this is shown in the various Courses under STEM: Technology Courses:

- □ Base Plate Aluminium Profile Plate of rectangular size
- □ Pick & Place Kit for demonstrating Pick and Place application
- □ Palletizing Ball Pallet Kit with ball feeder, balls and pallet
- Drawing Paint wit brush Kit
- □ Writing Writing Kit with papers
- □ Mobile Robot Mobile robot kit
- □ Motors & Operation Miniature motors and connectors
- □ Line Tracer Wheels, gears and connectors
- Circuit Design PCB
- □ Circuit Design Bread Board

9. BILL OF MATERIAL: ROBOT APPLICATION KIT FOR ENGINEERING

The following application kit is offered as Robot Application Kit. This is offered as a fully disassembled kit for the Trainees to design, build and program different applications. The STEM Courseware related to this is shown in the various Courses under STEM: Engineering Courses:

- □ Base Plate Aluminium Profile Plate of rectangular size
- □ Pick & Place Kit for demonstrating Pick and Place application
- □ Palletizing Ball Pallet Kit with ball feeder, balls and pallet
- Drawing Paint wit brush Kit
- □ Writing Writing Kit with papers
- □ Mobile Robot Mobile robot kit
- □ Motors & Operation Miniature motors and connectors
- □ Line Tracer Wheels, gears and connectors
- Circuit Design PCB
- □ Circuit Design Bread Board



10. BILL OF MATERIAL: ROBOT APPLICATION KIT FOR SCIENCE & MATHS

1 Set of Application Kit relevant to the Experiments mentioned in the Robotics in STEM Courseware (Science & Maths) will be supplied.

11. UTILITIES REQUIRED AT SITE

The Robotics In STEM Kit will be supplied and commissioned at the Computer Lab. The following utilities are required at site for commissioning, demonstration & training:

11.1. UTILITIES FOR MINI ROBOT

One Desktop computer on network as per the below specifications:

- Operating System : Windows 7 Professional or higher, Two free USB ports
- Processor: Intel 2,8 GHz or higher, RAM : at least 4 GB, 1 DVD Drive for software installation
- □ Graphic Card : NVIDIA GeForce at least 1 GB or equivalent, Recommended: 19" TFT Mon

Power Supply: Stable power supply is required as mentioned in the robot specifications.

Utilities for Mini Robot (Project): One Desktop computer as per the above specifications is required and hence the same computer as supplied above can be used.

11.2. UTILITIES FOR M-ROBOT & ARISTOSIM

Software can be installed with following requirements in the installation PC's:

Desktop System Requirements: The number of desktops is 10.

- □ Operating System : WIN 7 Professional or Higher (32 bit only)
- □ Intel Core 2 Duo E 4300 with 2 x 1,8 GHz or equivalent RAM : at least 4 GB
- Graphic Card : NVIDIA Quadro FX 550 or equivalent, 1 GB
- □ USB Interface & With 1 DVD Drive, 19" TFT Monitor, 2 free USB ports
- □ Local Hard Disk of minimum 2/4 GB
- □ The 10 computers should be on a common LAN Network.

Power Supply: Stable power supply is required for the computers



12. BILL OF MATERIAL: STEM COURSEWARE

12.1. ROBOTICS IN STEM COURSEWARE

ROBOTICS IN STEM COURSEWARE : 19 COURSES						
ROBOTICS IN STEM COURSEWARE : Over 250 Hours of Training						
CLASS	COURSES	DURATION (in Hours)				
	Science					
Class 8	Technology	56				
	Maths					
	Science					
Class Q	Technology	56				
	Engineering	50				
	Maths					
	Science					
Class 10	Technology	42				
	Engineering	42				
	Maths					
	Science					
Class 11	Technology	56				
	Engineering	50				
	Maths					
	Science					
Class 12	Technology	42				
	Engineering	42				
	Maths					



12.2. ROBOTICS IN STEM COURSEWARE FOR CLASS 8

CLASS	COURSES	COURSE DESCRIPTION	DURATION (in Hours)
		Metals and non-metals	
	Science	Force and pressure	
	Science	Mass, weight and density	
		Light	
		Introduction to robotics and robot structure	
Class 9	Tochnology	Classifications	40
	rechnology	Basic concept of motion	AURATION (in Hours)
		End effector	
		Linear equations in one variable	
	Mathe	Quadrilaterals	
	IVIALIIS	Comparing quantities	
		Introduction to graph	

SNO	COURSES	COURSE DESCRIPTION	
1	STEM : Science	This module will be covered as 1 hour classes. The classes will be scheduled in the lab where the metals/non-metals, force and pressure, mass, weight and density, light will be covered here using robots, its software and application kit. Different exercises will be conducted across this module to demonstrate the topics of force, pressure, mass, weight and density, light, etc. and its application in the real world. Experiments using this solution will be done in each time slot and the students will demonstrate the experiments to the rest of the class. The primary objectives achieved here are: understanding of the theoretical concepts of science, its application in technology, its relevance in the everyday real world. The secondary objective achieved here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module is scheduled to be aligned with the teaching schedule of the school thus becoming an enabler for the teacher and a learning enhancement tool for the student. It starts with a reckoner showcasing what was learnt in the previous year's thus enabling the teacher and allowing the student to connect the learning process between classes.	
2	STEM: Technology	This module follows the STEM: Science Modules and thus enforces the learning of the abstract concepts thru technology. The classes will be scheduled in the lab where the concepts of robotics and automation, history, classification, end effector - gripper, types, working and real time application will be covered here using robots and its software. Students will perform different exercises using the equipment and thus experience different aspects of technology used today. Experiments using this solution will be done in each time slot and the students will demonstrate the experiments to the rest of the class. The primary objectives achieved here are: exposure to technology, its relevance in the everyday real world. The secondary objective achieved	



		here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module follows the STEM: Science Modules and thus enforces the learning of the
		abstract concepts thru technology.
SNO	COURSES	COURSE DESCRIPTION
		This module will be covered as 1 hour classes. The classes will be scheduled in the lab where the concepts of linear equation in one variable, quadrilaterals, comparing quantities, Introduction to graph will be covered using robots, its software and application kit. Experiments using this solution will be done in each time slot and the students will demonstrate the experiments to the rest of the class. The primary objectives achieved here are: understanding of the linear equation, quadrilaterals,
3	STEM: Maths co	mparing quantities concepts of maths, its application in technology, its relevance in the everyday real world. The secondary objective achieved here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module is scheduled to be aligned with the teaching schedule of the school thus becoming an enabler for the teacher and a learning enhancement tool for the student.



12.3. ROBOTICS IN STEM COURSEWARE FOR CLASS 9

CLAS	SS	COURSES	COURSE DESCRIPTION	DURATION (in Hours)
			Fundamental units	
			motion	
		Science	Force & law of motion	
			Gravitation	
			Work and energy	
			Robot anatomy	64
		Technology	Robot axis and coordinate system (frame)	
			Robot motions	
Class 9			Type of motion and human anatomy vs robot anatomy & Technologies	
			Sensors & Instrumentation – Introduction	
	-	Engineering	Measuring system – Calibration Techniques	
			Basic Programmable logic controllers	
			Number system	
		Maths	Algebra	
			Coordinate geometry	
			Geometry - Angles, circles and triangles	
			Measurement - surface area and volume	

SNO	COURSES	COURSE DESCRIPTION
4	STEM : Science	This module will be covered as 1 hour classes. The classes will be scheduled in the lab where the concepts of motion, gravity will be discussed and taught using Robots and its software. Different exercises will be conducted across this module to demonstrate the topics of motion and gravity and its application in the real world. Experiments using this solution will be done in each time slot and the students will demonstrate the experiments to the rest of the class. The primary objectives achieved here are: understanding of the theoretical concepts of science, its application in technology, its relevance in the everyday real world. The secondary objective achieved here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module is scheduled to be aligned with the teaching schedule of the school thus becoming an enabler for the teacher and a learning enhancement tool for the student.
SNO	COURSES	COURSE DESCRIPTION



5	STEM: Technology	This module will be covered as 1 hour classes. The classes will be scheduled in the lab where the concepts of robot structure - links and joints, robot motions, laws, coordinates system will be covered here using robots and its software. Students will perform different exercises using the equipment and thus experience different aspects of technology used today. Experiments using this solution will be done in each time slot and the students will demonstrate the experiments to the rest of the class. The primary objectives achieved here are: exposure to technology, its relevance in the everyday real world. The secondary objective achieved here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module follows the STEM: Science Modules and thus enforces the learning of the abstract concepts thru technology. It starts with a reckoner showcasing what was learning in the previous year's thus enabling the teacher and allowing the student to connect the learning process between classes.
6	STEM: Engineering	This module will be covered as 1 hour classes. The classes will be scheduled in the lab where the following areas will be covered: Programming of specific robot application using various shapes, path planning, programming of robot application like pick and place, palletizing, assembly using robots and software. Students will perform different exercises using the equipment and thus experience different aspects of engineering used today. Experiments using this solution will be done in each time slot and the students will demonstrate the experiments to the rest of the class. Engineering is an aspirational area for today's students and this prepares the students thru a better understanding of the field of engineering and technology. This module focusses on developing the analytical skills and problem solving techniques of these students - thus allowing them to envision various career opportunities. The primary objectives achieved here are: exposure to engineering, relevance of the theoretical aspects of learning to engineering, its relevance in the everyday real world. The secondary objective achieved here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module follows the STEM: Maths Modules and connects concepts of science and maths to technology. It starts with a reckoner showcasing what was learning in the previous year's thus enabling the teacher and allowing the student to connect the learning process between classes.
7	STEM: Maths	This module will be covered as 1 hour classes. The classes will be scheduled in the lab where the concepts of number system, algebra, coordinate geometry, geometry-angles, circles and triangle will be covered using robots, its software and application kit. Experiments using this solution will be done in each time slot and the students will demonstrate the experiments to the rest of the class. The primary objectives achieved here are: understanding of the theoretical concepts of maths, its application in technology, its relevance in the everyday real world. The secondary objective achieved here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module is scheduled to be aligned with the teaching schedule of the school thus becoming an enabler for the teacher and a learning enhancement tool for the student.



12.4. ROBOTICS IN STEM COURSEWARE FOR CLASS 10

CLASS	COURSES	COURSE DESCRIPTION	DURATION (in Hours)
	Science	Electricity	
	Science	Magnetic effects of electric current	
		Basics of input and output devices	
		Transmission system & Technologies	
	Technology	Degree Of Freedom (D.O.F)	64
	теспноюду	Jog methods & type	
		Robot programming - motion commands &	
Class 10		math command	
		Electronic devices & Circuits	
	Engineering	Electrical & Power systems	
	Engineering	Practicals - Real time application (Pick and place, palletizing)	
	Maths	Real numbers	
		Geometry	
		Measurement - surface area and volume	

SNO	COURSES	COURSE DESCRIPTION
8	STEM : Science	This module will be covered as 1 hour classes. The classes will be scheduled in the lab where the concepts of electricity, electric current, components and circuits will be covered here using robot and robot controller. Different exercises will be conducted across this module to demonstrate the topics of electricity, electric current etc. and its application in the real world. Experiments using this solution will be done in each time slot and the students will demonstrate the experiments to the rest of the class. The primary objectives achieved here are: understanding of the theoretical concepts of science, its application in technology, its relevance in the everyday real world. The secondary objective achieved here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module is scheduled to be aligned with the teaching schedule of the school thus becoming an enabler for the teacher and a learning enhancement tool for the student. It starts with a reckoner showcasing what was learnt in the previous year's thus enabling the teacher and allowing the student to connect the learning process between classes.
SNO	COURSES	COURSE DESCRIPTION



9	STEM: Technology	the lab where the concepts of robot programming - point-to-point, joint, delay and programming methods, commands - if, label, math command using robots and software. Students will perform different exercises using the equipment and thus experience different aspects of technology used today. Programming is an important aspect in today's learning and it offers the students to explore and innovate thru development of application on various platforms. This module focusses on developing the analytical and programming skills of these students - thus allowing them to envision various career opportunities. Experiments using this solution will be done in each time slot and the students will demonstrate the experiments to the rest of the class. The primary objectives achieved here are: exposure to technology, its relevance in the everyday real world. The secondary objective achieved here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module follows the STEM: Science Modules and thus enforces the learning of the abstract concepts thru technology. It starts with a reckoner showcasing what was learnt in the previous year's thus enabling the teacher and allowing the student to connect the learning process between classes.
10	STEM: Engineering	Employability skills is the key focus in this module. Thru this module, the students are equipped with employability skills to become part of the structured work force, choose to take up further vocational courses or opt for higher education. This module will be covered as 1 hour classes. The classes will be scheduled in the lab where the following areas will be covered: Building of robot application using various shapes, path planning, programming of robot application like pick and place, palletizing, assembly using robots and software. Students will perform different exercises using the equipment and thus experience different aspects of engineering used today. There is shift in experiential learning in this module wherein the students start working together in groups to physically construct the application and then program and execute. This is a project based module and the project (Experiments using this solution) will be done across 2-4 classes and the students will demonstrate the projects to the rest of the class. Each project will be unique and thus also allow the students to demonstrate: innovative thinking, critical path approach, presentation skills, team working, leadership skills, ability to address conflicts, conflict resolution, convincing of ideas and so on. Engineering is an aspirational area for today's students and this prepares the students thru a better understanding of the field of engineering and technology. This module focusses on developing the analytical skills and problem solving techniques of these students - thus allowing them to envision various career opportunities. The primary objectives achieved here are: exposure to engineering, relevance of the theoretical aspects of learning to engineering, its relevance in the everyday real world. The secondary objective achieved here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better inf



	This module will be covered as 1 hour classes. The classes will be scheduled in the
STEM:	lab where the concepts of real numbers, geometry, measurement - surface, area and volume will be covered using robots, its software and application kit. Different exercises will be conducted across this module to demonstrate the topics of real numbers, geometry, measurement etc. and its application in the real world. Experiments using this solution will be done in each time slot and the students will demonstrate the experiments to the rest of the class. The primary objectives achieved here are: understanding of the theoretical concepts of maths, its application in technology, its relevance in the everyday real world. The
Maths	secondary objective achieved here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module is scheduled to be aligned with the teaching schedule of the school thus becoming an enabler for the teacher and a learning enhancement tool for the student. It starts with a reckoner showcasing what was learnt in the previous year's thus enabling the teacher and allowing the student to connect the
	STEM: Maths



12.5. ROBOTICS IN STEM COURSEWARE FOR CLASS 11

CLASS	COURSES	COURSE DESCRIPTION	DURATION (in Hours)
		Units and measurements	
		Motion in straight line	
	Science	Law of motion	
		Work, energy and power	
		Gravitation	
	Tashralasi	Input device (sensor and switching devices) & Technologies	64
	rechnology	Output device (motor and types) & Technologies	
Class 11	Engineering	Electric circuits - working & schematic symbols	
		Building circuits - on bread boards	
		Building circuits - on PCB	
		PIC controller - working and basic programming	
		Coordinates	
		Straight line	
	Math		
	S	Quadratic equation	
		Introduction to 3D geometry	
		Trigonometry functions	

SNO	COURSES	COURSE DESCRIPTION
12	STEM : Science (Physics)	This module will be covered as 1 hour classes. The classes will be scheduled in the lab where the concepts and laws of gravitation, work, energy, power, motion in straight line will be covered here using robots, its software and application kit. Different exercises will be conducted across this module to demonstrate the topics of gravity, energy, power etc. and its application in the real world. Experiments using this solution will be done in each time slot and the students will demonstrate the experiments to the rest of the class. The primary objectives achieved here are: understanding of the theoretical concepts of science, its application in technology, its relevance in the everyday real world. The secondary objective achieved here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module is scheduled to be aligned with the teaching schedule of the school thus becoming an enabler for the teacher and a learning enhancement tool for the student. It starts with a reckoner showcasing what was learnt in the previous year's thus enabling the teacher and allowing the student to connect the learning process between classes.

13	STEM: Technology	This module will be covered as 1 hour classes. The classes will be scheduled in the lab where the concepts and working principles of input & output devices (switches, sensor & motors) will be covered here using STEM kit. Students will perform different exercises using the equipment and thus experience different aspects of technology used today. Electronics is an important aspect in today's life and this module offers the students to explore basic electronics. This module focusses on developing a base understanding of these concepts thus ensuring that when they proceed towards higher education and career they are amply equipped with understanding and skills required to excel in these fields. Experiments using this solution will be done in each time slot and the students will demonstrate the experiments to the rest of the class. The primary objectives achieved here are: exposure to technology, its relevance in the everyday real world. The secondary objective achieved here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module follows the STEM: Science Modules and thus enforces the learning of the abstract concepts thru technology. It starts with a reckoner showcasing what was learnt in the previous year's thus enabling the teacher and allowing the student to connect the learning process between classes.
14	STEM: Engineering	This module will be covered as 1 hour classes. The classes will be scheduled in the lab where the concepts of developing electric circuits using schematic symbols, building of circuit on breadboards and PCB and PIC controller - working and programming concepts. Students will perform different exercises using the equipment and thus experience different aspects of engineering used today. There is higher shift in experiential learning in this module wherein the students start working together in groups to physically design, construct the application and then program and execute. In this module, students start thinking about designing applications connected to their life and experiences. This allows student creativity at its best. This is a project based module and the project (Experiments using this solution) will be done across 2-4 classes and the students will demonstrate the projects to the rest of the class. Each project will be unique and thus also allow the students to demonstrate: innovative thinking, critical path approach, presentation skills, team working, leadership skills, ability to address conflicts, conflict resolution, convincing of ideas and so on. Engineering is an aspirational area for today's students and this prepares the students thru a better understanding of the field of engineering and technology. This module focusses on developing the analytical skills and problem solving techniques of these students - thus allowing them to envision various career opportunities. The primary objectives achieved here are: relating knowledge to application, communication skills thru demonstration skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module follows the STEM: Maths Modules and connects concepts of science and maths to technology. It starts with a reckoner showcasing what was learnt in the previous year's thus enabling the teacher and allowing the stud

SNO	COURSES	COURSE DESCRIPTION			
15	STEM MATHS	This module will be covered as 1 hour classes. The classes will be scheduled the lab where the concepts of coordinates, straight line, quadratic equation, geometry will be covered using robots, software. Experiments using this solut will be done in each time slot and the students will demonstrate the experime to the rest of the class. The primary objectives achieved here are: understand of the theoretical concepts of maths, its application in technology, its relevar in the everyday real world. The secondary objective achieved here are: relat knowledge to application, communication skills thru demonstration, confider building thru problem solving techniques and overall wellbeing a enhancement of life skills thru access to better infrastructure and learn techniques. This module is scheduled to be aligned with the teaching schedule the school thus becoming an enabler for the teacher and a learn enhancement tool for the student.			

12.6. ROBOTICS IN STEM COURSEWARE FOR CLASS 12

CLASS	COURSES	COURSE DESCRIPTION	DURATION (in Hours)
	Science	Communication system	40
	Science	Semiconductor electronics	
	Technology	Path planning	
		Motor speed control – methods	
		PIC controller - Programming syntax	
Class 12	Engineering	Engineering components and blueprint reading	
		Principles to assemble, test and operate a robot	
		Design & Fabrication Project	
	Maths	Transformations	
		Vector algebra	
		Matrix	

SNO	COURSES	COURSE DESCRIPTION		
		This module will be covered as 1 hour classes. The classes will be scheduled in		
		the lab where the concepts of digital electronics, communication system will be		
		covered here using robots. Different exercises will be conducted across this		
		module to demonstrate the topics of electronics, communication etc. and its		
		application in the real world. Experiments using this solution will be done in		
		each time slot and the students will demonstrate the experiments to the rest		
	STEM :	of the class. The primary objectives achieved here are: understanding of the		
16	Science theore	tical concepts of science, its application in technology, its relevance in		
	(Physics)the e	<mark>e e</mark> veryday real world. The secondary objective achieved here are: relating		
		knowledge to application, communication skills thru demonstration,		
		confidence building thru problem solving techniques and overall wellbeing		
		and enhancement of life skills thru access to better infrastructure and learning		
		techniques. This module is scheduled to be aligned with the teaching schedule		
		of the school thus becoming an enabler for the teacher and a learning		
		enhancement tool for the student.		
	STEM: Technology	This module will be covered as 1 hour classes. The classes will be scheduled in		
		the lab where the concepts of mobile robot working and method of path		
		detections, PIC controller programming concepts developments. Students will perform different exercises using the equipment and thus experience different		
		aspects of technology used today. Electronics is an important aspect in today's		
17		life and this module offers the students to explore basic electronics. This		
		module focusses on developing a base understanding of these concepts thus		
		ensuring that when they proceed towards higher education and career they are		
		amply equipped with understanding and skills required to excel in these fields.		
		Experiments using this solution will be done in each time slot and the students		
		will demonstrate the experiments to the rest of the class. The primary		

SNO	objectives achieved here are: exposure to technology, its relevance everyday real world. The secondary objective achieved here are: rela knowledge to application, communication skills thru demonstrat confidence building thru problem solving techniques and overall we enhancement of life skills thru access to better infrastructure and le techniques. This module follows the STEM: Science Modules and thu the learning of the abstract concepts thru technology. It starts with a showcasing what was learnt in the previous year's thus enabling the and allowing the student to connect the learning process between c SNO COURSES COURSES	
18	STEM: Engineering	Enjoyability skills are the key focus in these modules. Third this flocture, the students are equipped with employability skills to become part of the structured work force, choose to take up further vocational courses or opt for higher education. This module will be covered as 1 hour classes. The classes will be scheduled in the lab where the following areas will be covered: Engineering components, blueprint reading and principles to assemble, test and operate a robot. Students will perform different exercises using the equipment and thus experience different aspects of engineering used today. There is higher shift in experiential learning in this module wherein the students start working together in groups to physically design, construct the application and then program and execute. In these module students start thinking about designing applications connected to their life and experiences. This allows student creativity at its best. This is a project based module and the project (Experiments using this solution) will be done across 2-4 classes and the students will demonstrate the projects to the rest of the class. Each project will be unique and thus also allow the students to demonstrate: innovative thinking, critical path approach, presentation skills, team working, leadership skills, ability to address conflicts, conflict resolution, convincing of ideas and so on. Engineering is an aspirational area for today's students and this prepares the students thru a better understanding of the field of engineering and technology. This module focusses on developing the analytical skills and problem solving techniques of these students - thus allowing them to envision various career opportunities. The primary objectives achieved here are: elating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module follows the STEM: Maths Mod

SNO	COURSES	COURSE DESCRIPTION		
19	STEM: Maths	This module will be covered as 1 hour classes. The classes will be scheduled in the lab where the concepts of transformations, vector algebra, and matrix will be covered using robots, software. Experiments using this solution will be done in each time slot and the students will demonstrate the experiments to the rest of the class. The primary objectives achieved here are: understanding of the theoretical concepts of maths, its application in technology, its relevance in the everyday real world. The secondary objective achieved here are: relating knowledge to application, communication skills thru demonstration, confidence building thru problem solving techniques and overall wellbeing and enhancement of life skills thru access to better infrastructure and learning techniques. This module is scheduled to be aligned with the teaching schedule of the school thus becoming an enabler for the teacher and a learning enhancement tool for the student.		

13. DELIVERY SCHEDULE

Site readiness is the scope of the customer and must meet the technical scope as mentioned in this document.

13.1. DELIVERY SCHEDULE

Delivery schedule comprises of supply of kits and Train the Teachers. Train the Teachers will happen independent of kits and will be scheduled and completed before the completion of supply of kits.

Delivery schedule for the supply of kits will be as follows:

SCHEDULE OF SUPPLY			
Week of Supply	No. of Schools	Cumulative Schools supplied till date	
Week 8	5	5	
Week 10	5	10	
Week 12	8	18	
Week 14	8	26	
Week 16	10	36	
Week 18	10	46	
Week 20	12	58	
Week 22	12	70	
Week 24	15	85	
Week 26	15	100	
Week 28	18	118	
Week 30	20	138	
Week 32	22	160	
Week 34	25	185	
Week 36	25	210	
Week 38	25	235	
Week 40	25	260	
Week 42	25	285	
Week 44	25	310	
Week 46	25	335	
Week 48	25	360	
Week 50	25	385	
Week 52	25	410	
Week 54	25	435	
Week 56	25	460	
Week 58	20	480	
Week 60	20	500	

13.2. Commissioning and Demonstration

The kits will be commissioned and demonstrated on the same day of supply.

13.3. WARRANTY

Warranty offered is 12 months from the date of commissioning or 15 months from the date of supply whichever is earlier. Warranty is covered for manufacturing defects.

13.4. SITE CLEARANCE BY MTC:

MTC will visit all the site and prepare a site clearance report. The site clearance responsibilities are summarized below.

- □ MTC will submit a report regarding site clearance for the acceptance of goods at each site. The site clearance will include availability of space (Computer lab) in each site, Technical readiness as mentioned under the SCOPE OF THE CUSTOMER
- □ In case the site is not ready and hence not cleared, MTC will submit an appropriate report to the customer. Within 2 weeks of the MTC report date, the customer must get the site ready in the same school or find an alternative school (which has a ready site) within the same district.

14. SUMMARY OF COMMERCIAL OFFER

Our Commercial offer is being given for entire scope of supply and services. The offer will be applicable as per the number of schools given in the purchase order ie., the value of the "Robotics in STEM" solution remains the same irrespective of the number of schools placing the order, the Scope Of Supply & Services change based on the summary below.

Category	Туре	Scope of Supply & Services	100-500 schools	More than 50 but less than 100 schools
Supply	Hardware	Robotics in STEM Kit:	\checkmark	\checkmark
Supply	Software	Robotics in STEM Software	\checkmark	\checkmark
Supply	Courseware	Courseware: Interactive eLearning licenses	\checkmark	
Supply	Courseware	Courseware: PDF Books	\checkmark	\checkmark
Services	Services	Commissioning & Demonstration	\checkmark	\checkmark
Services	Services	Warranty	\checkmark	\checkmark
Services	Services	Mentoring: Mentors during warranty period	1	\checkmark
Services	Services	Monitoring: Monitoring through LMS during warranty period	\checkmark	
Services	Training	Train the Teachers: Level 1: Centralised training for 1 week in Term1	\checkmark	\checkmark
Services	Training	Train the Teachers: Level 2: Centralised training for 1 week in Term2	\checkmark	
Services	Services	Workshop and Competitions		

CONTACT DETAILS

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